

A STUDY OF CERTAIN NEW CURVES IN AN EUCLIDEAN SPACE OF THREE DIMENSIONS-III

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Analogous to λ_0 -curves and λ_N -curves defined by Bajpai and Rastogi [5, 6], in this paper we have defined a new curve called λ_R -curve, which is such that its rectifying plane contains the vector $d^3\lambda^i/ds^3$, where λ^i are the contra-variant components of a unit vector in the direction of the line 1 of the congruence passing through a point P . We have studied some curvature properties of this curve in an Euclidean space of three dimensions *visa-a-vis* other well-known curves.

PRELIMINARIES

Let $S : x^i = x^i(u^\alpha)$, ($i = 1, 2, 3$ and $\alpha = 1, 2$), be the surface of reference of a rectilinear congruence, a line 1 of which is given by the direction cosines

$$\lambda^i = \lambda^i(u^\alpha), \lambda^i \lambda^i = 1. \quad \dots (1.1)$$

We assume that x^i and λ^i are continuous along with their partial derivatives up to the required order. At any point $P(x^i)$ of S , λ^i is expressible as [3]

$$\lambda^i = p^\alpha x^i_{,\alpha} + q X^i, \quad \dots (1.2)$$

where p^α are the contra-variant components of a vector in S at P and q is a scalar function, X^i are the direction cosines of the normal to S at P and $x^i_{,\alpha}$ denotes the covariant derivative of x^i with respect to u^α based on the fundamental tensor of S , $g_{\alpha\beta} = x^i_{,\alpha} \cdot x^i_{,\beta}$.

The Gauss and Weingarten equations Eisenhart [2] are given by $x^i_{,\alpha\beta} = d_{\alpha\beta} X^i$, $X^i_{,\alpha} = -d_\alpha^\delta x^i_{,\delta}$, where $d_{\alpha\beta}$ is the second fundamental tensor of the surface S .

Let us consider a curve $C: x^i = x^i(s)$ on S , then the intrinsic derivative of x^i , $d x^i/ds$ and $d^2 x^i/ds^2$ are expressed as

$$x'^i = d x^i/ds = x^i_{,\alpha} u'^\alpha, x''^i = d^2 x^i/ds^2 = \rho^\alpha x^i_{,\alpha} + X^i k_n = k\beta^i \quad \dots (1.3)$$

and
$$x'''^i = d^3 x^i/ds^3 = (\rho^\alpha_{,\beta} - k_n d_{\beta 0} g^{\alpha 0}) x^i_{,\alpha} u'^\beta + (k_{n,\beta} + \rho^\alpha d_{\alpha\beta}) X^i u'^\beta, \quad \dots (1.4)$$

where, primes indicate the differentiation with respect to arc-length s , p^α are the components of the geodesic curvature vector of the curves C and k_n is the normal curvature of the surface in the direction of curves C [2].

SOME INTRINSIC DERIVATIVES

If we consider a vector λ^i in the direction of the curves of the congruence- λ , following intrinsic derivatives can be obtained:

$$\lambda^i = d\lambda^i/ds = \lambda^i_{,\alpha} u'^{\alpha} = (\mu^{\gamma}_{\alpha} x^i_{,\gamma} + \nu_{\alpha} X^i) u'^{\alpha} \quad \dots (2.1)$$

where

$$\mu^{\gamma}_{\alpha} = p^{\gamma}_{,\alpha} - q d_{\alpha\beta} g^{\beta\gamma}, \nu_{\alpha} = q_{,\alpha} + p^{\beta} d_{\alpha\beta}. \quad \dots (2.2)$$

For a normal congruence $\mu^{\gamma}_{\alpha} = -d^{\gamma}_{\alpha}$ and $\nu_{\alpha} = 0$, while for a congruence formed by tangents to a one parameter family of curves $\mu^{\gamma}_{\alpha} = p^{\gamma}_{,\alpha}$ and $\nu_{\alpha} = p^{\beta} d_{\alpha\beta}$. We know that $\lambda^i = 1$, therefore we can obtain $\lambda^i_{,\alpha} = 0$, which gives $p_{\gamma} \mu^{\gamma}_{\alpha} + q \nu_{\alpha} = 0$.

Differentiating $\lambda^i_{,\alpha}$ covariantly with respect to u'^{β} , we get

$$\lambda^i_{,\alpha\beta} = M^i_{\alpha\beta} x^i_{,\gamma} + N_{\alpha\beta} X^i, \quad \dots (2.3)$$

where

$$M^i_{\alpha\beta} = \mu^{\gamma}_{\alpha,\beta} - \nu_{\alpha} d_{\beta\theta} g^{\theta\gamma}, N_{\alpha\beta} = \nu_{\alpha,\beta} + \mu^{\gamma}_{\alpha} d_{\gamma\beta}. \quad \dots (2.4)$$

The intrinsic derivative of $d\lambda^i/ds$, represented by λ''^i along C can be obtained as follows:

$$\lambda''^i = (M^i_{\alpha\beta} u'^{\alpha} u'^{\beta} + \mu^{\gamma}_{\alpha} u''^{\alpha}) x^i_{,\gamma} + (N_{\alpha\beta} u'^{\alpha} u'^{\beta} + \nu_{\alpha} u''^{\alpha}) X^i. \quad \dots (2.5)$$

such that

$$p_{\gamma} M^i_{\alpha\beta} + q N_{\alpha\beta} + \mu_{\alpha\delta} \mu^{\delta}_{\beta} + \nu_{\alpha} \nu_{\beta} = 0. \quad \dots (2.6)$$

From equation (2.3) we can get

$$\lambda^i_{,\alpha\beta\gamma} = (M^{\theta}_{\alpha\beta,\gamma} - N_{\alpha\beta} d_{\gamma\delta} g^{\delta\theta}) x^i_{,\theta} + X^i (M^{\theta}_{\alpha\beta} d_{\theta\gamma} + N_{\alpha\beta,\gamma}). \quad \dots (2.7)$$

such that

$$q \{ M^{\theta}_{\alpha\beta} (q d_{\theta\gamma} + \mu_{\theta\gamma} - p_{\theta,\gamma}) + M^{\theta}_{\beta\gamma} \mu_{\theta\alpha} - M_{\beta\theta,\gamma} \mu^{\theta}_{\alpha} \} - \mu^{\theta}_{\alpha} \mu^{\theta}_{\beta} d_{\theta\gamma} p_{\gamma} - N_{\alpha\beta} (\mu^{\theta}_{\gamma} p_{\theta} + q p^{\theta} d_{\theta\gamma} + q q_{,\gamma}) = 0. \quad \dots (2.8)$$

The intrinsic derivative of $d^2\lambda^i/ds^2$ along C which is represented by λ'''^i can be obtained in the following form

$$\lambda'''^i = (x^i_{,\gamma} A^{\gamma} + B X^i), \quad \dots (2.9)$$

where

$$A^{\gamma} = [\mu^{\gamma}_{\alpha} u'''^{\alpha} + u''^{\alpha} u'^{\beta} (2M^{\gamma}_{\alpha\beta} + M^{\gamma}_{\beta\alpha}) + u'^{\alpha} u'^{\beta} u'^{\delta} (M^{\gamma}_{\alpha\beta,\delta} - N_{\alpha\beta} d^{\gamma}_{\delta})] \quad \dots (2.10 a)$$

and

$$B = [\nu_{\alpha} u'''^{\alpha} + u''^{\alpha} u'^{\beta} (2N_{\alpha\beta} + N_{\beta\alpha}) + u'^{\alpha} u'^{\beta} u'^{\delta} (d_{\gamma\delta} M^{\gamma}_{\alpha\beta} + N_{\alpha\beta,\delta})]. \quad \dots (2.10 b)$$

λ_R -CURVES

Definition 3.1. A curve C in an Euclidean space of three dimensions shall be called λ_R -curve, if the vector λ'''^i lies in the rectifying plane at the point.

The differential equation of the rectifying plane to a curve C at a point P is [2]:

$$(x^i - x^j) (\rho^{\alpha} x^i_{,\alpha} + X^j k_n) = 0. \quad \dots (3.1)$$

For C to be a λ_R -curve $x^i = x^i + t \lambda'''^i$ must satisfy (2.1) for all t . Using this and (2.9) in (3.1), we get on simplification

$$A^{\alpha} \rho_{\alpha} + B k_n = 0, \quad \dots (3.2)$$

as the differential equation of a λ_R -curve.

Remarks. In an earlier paper Rastogi and Bajpai [4], while studying the properties of the vector λ'''^i , obtained equation (3.2) as the differential equation of a Super Darboux curve.

Alternatively, let us suppose that α^i , β^i and γ^i be respectively the direction cosines of unit tangent, principal normal and binormal to a λ_R -curve C , then we can express λ'''^i as follows:

$$\lambda'''^i = a \alpha^i + b \gamma^i, \quad \dots (3.3)$$

where a and b are arbitrary constants to be determined.

Let ψ be the angle between the vectors α^i and λ''''^i , then for $D|\lambda''''^i| = 1$, we can obtain

$$a = D^{-1} \cos \psi, b = \pm D^{-1} \sin \psi. \quad \dots (3.4)$$

Substituting in equation (3.3), from equation (2.9) and (3.4), together with

$$\tau\gamma^i = -(d\beta^i/ds + k\alpha^i), \quad \dots (3.5)$$

we obtain on simplification

$$x^i, \gamma A^\gamma + B X^i = D^{-1} x^i, \gamma [u'^\gamma \cos \psi \pm \tau^{-1} \sin \psi \{ \rho^\gamma k' k^{-2} - k u'^\gamma - k^{-1} (\rho^\gamma, \beta - k_n d'_{\beta}) u' \beta \}] \pm (D \tau k)^{-1} (k' k^{-1} k_n - d_{\alpha\beta} \rho^\alpha u'^\beta - k_n') X^i \sin \psi, \quad \dots (3.6)$$

which easily leads to

$$\eta^\gamma \equiv A^\gamma - D^{-1} [u'^\gamma \cos \psi \pm \tau^{-1} \sin \psi \{ \rho^\gamma k' k^{-2} - k u'^\gamma - k^{-1} (\rho^\gamma, \beta - k_n d'_{\beta}) u' \beta \}] = 0 \quad \dots (3.7a)$$

$$\text{And} \quad B = \pm (D \tau k)^{-1} (k' k^{-1} k_n - d_{\alpha\beta} \rho^\alpha u'^\beta - k_n') \sin \psi, \quad \dots (3.7b)$$

where η^γ shall be called the λ_R -curvature vector of a curve C .

Equation (3.7a) represents an alternative form of differential equation of λ_R -curves.

In case the vectors α^i and λ''''^i are parallel, *i.e.*, $\psi = 0$, equations (3.7a) and (3.7b) respectively reduce to $\eta^\gamma = 1 A^\gamma - D^{-1} u'^\gamma = 0$ and $B = 0$, *i.e.* equation (3.2) will imply $A^\alpha \rho_\alpha = 0$. Also $B = 0$, represents the differential equation of generalized Darboux curves [4]. Hence we have:

Theorem 3.1. In an Euclidean space of three dimensions, if the vector λ''''^i is parallel to α^i , λ_R -curve satisfies the differential equation $A^\gamma - D^{-1} u'^\gamma = 0$ or $A^\alpha \rho_\alpha = 0$ and it reduces to a generalized Darboux curve.

λ_R -CURVATURE

Let K_R represents the λ_R -curvature of a curve C , *i.e.*, the magnitude of the vector with contravariant components η^γ , then we can obtain after some lengthy calculation

$$K_R^2 = A^\gamma A_\gamma - 2D^{-1} [A_\gamma u'^\gamma (\cos \psi \pm k \tau^{-1} \sin \psi) \pm (k \tau)^{-1} \{ \sin \psi (k^{-1} k' A_\gamma \rho^\gamma - A_\gamma \rho'^\gamma + k_n d_{\gamma\beta} A^\gamma u'^\beta) - (1/2) D^{-1} \sin 2\psi (k_g^2 + u'^\gamma \rho'_\gamma) \}] + D^{-2} [\cos^2 \psi + \tau^{-2} \sin^2 \psi \{ k'^2 k^{-4} k_g^2 + k^{-2} \rho'^\gamma \rho'_\gamma - k^2 - 2k_n^2 + 2u'^\gamma \rho'_\gamma - 2k^{-3} k' (\rho^\gamma \rho'_\gamma - k_n d_{\gamma\beta} u'^\gamma \rho^\beta) + k^{-2} k_n d_{\gamma\beta} u'^\beta (d'_\theta u'^\theta - 2\rho'^\gamma) \}], \quad \dots (4.1)$$

where $k_g^2 = k^2 - k_n^2$. Thus we have

Theorem 4.1. In a three-dimensional Euclidean space λ_R -curvature K_R of a curve C is given by (4.1) and it vanishes identically for a λ_R -curve.

For $\psi = 0$, equation (4.1) reduces to

$$K_R^2 = A^\gamma A_\gamma - 2D^{-1} A_\gamma u'^\gamma + D^{-2}, \quad \dots (4.2)$$

which implies.

Theorem 4.2. In a three-dimensional Euclidean space if the vector λ''''^i is parallel to α^i , λ_R -curvature K_R of a curve C is given by (4.2).

CURVATURE OF A λ_R -CURVE

Let α^i , β^i and γ^i be respectively the direction cosines of unit tangent, principal normal and binormal to a curve C , then for a λ_R -curve we can express γ^i in the following form:

$$\gamma^i = p \alpha^i + q \lambda'''^i, \quad \dots (5.1)$$

where p and q are arbitrary constants to be determined.

Let ψ be the angle between the vectors α^i and λ'''^i , then for $D |\lambda'''^i| = 1$

$$p = -\cot \psi, q = D \operatorname{cosec} \psi. \quad \dots (5.2)$$

From equations (5.1) and (5.2), we get

$$\gamma^i = \operatorname{cosec} \psi (D \lambda'''^i - \alpha^i \cos \psi).$$

Comparing equations (3.5) and (5.3), we get on simplification

$$k^2 = \rho_{\alpha, \beta} u'^\alpha u'^\beta - k_n^2.$$

Hence we have:

Theorem 5.1. The curvature of a λ_R -curve C , in an Euclidean space of three dimensions is given by (5.4) and this curvature will vanish if and only if the curve satisfies

$$(\rho_{\alpha, \beta} - d_{\alpha\gamma} d_{\beta\delta} u'^\delta) u'^\alpha, u'^\beta = 0. \quad \dots (5.5)$$

From equation (1.3) we can easily obtain

$$k^2 = \rho^\alpha, \rho_\alpha + k_n^2, \quad \dots (5.6)$$

therefore, comparing equations (5.4) and (5.6) we get

$$k^2 = (1/2) (\rho_{\alpha, \beta} u'^\alpha u'^\beta + \rho^\alpha \rho_\alpha) \quad \dots (5.7)$$

and

$$k_n^2 = (1/2) (\rho_{\alpha, \beta} u'^\alpha u'^\beta - \rho^\alpha \rho_\alpha) \quad \dots (5.8)$$

Hence we have :

Theorem 5.2. The curvature of a λ_R -curve C , in an Euclidean space of three dimensions satisfies equation (5.7) while the normal curvature of the surface is given by equation (5.8).

Substituting the values of α^i , β^i and γ^i , with the help of equations (5.3) and (5.4), we can obtain

$$\tau = -(BD)^{-1} \sin \psi \{(k_n/k)' + k^{-1} d_{\alpha\beta} \rho^\alpha u'^\beta\}. \quad \dots (5.9)$$

If we assume that $d_{\alpha\beta} \rho^\alpha u'^\beta = 0$, equation (5.9) gives $\tau = -(BD)^{-1} \sin \psi \{(k_n/k)'$ and conversely. Hence we have:

Theorem 5.3. The necessary and sufficient condition for λ_R -curves to be conjugate to their curvature vectors, is given by $\tau = -(BD)^{-1} \sin \psi (k_n/k)'$.

If we assume $\tau = 0$, $d_{\alpha\beta} \rho^\alpha u'^\beta = -k (k_n/k)'$. Conversely, if $d_{\alpha\beta} \rho^\alpha u'^\beta = -k (k_n/k)'$, we get $\tau = 0$. Hence we have:

Theorem 5.4. The necessary and sufficient condition for a λ_R -curve to have vanishing torsion is given by $d_{\alpha\beta} \rho^\alpha u'^\beta = -k (k_n/k)'$.

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